

Houdini FX

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POPs

Random Spin:

```
// The following makes it random:  
axis = rand(@id) - set(0.5, 0.5, 0.5);  
spinspeed *= rand(@id+0.1);
```

Python

Fun Shelf Scripts

Version up sops that have a "version" parm - I use this to version up a lot of exports in tops or rops:

```
import hou
nodes = hou.selectedNodes()
for x in nodes:
    ver = x.parm("version").eval() + 1
    x.parm("version").set(ver)
```

Send a ROP fetch to TOPs name "topnet1" for convenient cooking.:

```
import hou
nodes = hou.selectedNodes()
topnet = hou.node("/obj/topnet1")
frb = round((hou.playbar.frameRange()[1] - hou.playbar.frameRange()[0]) / 2)

if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")
if not hou.node("/obj/topnet1/rangegenerate_start"):
    rg = topnet.createNode("rangegenerate")
    rg.setName("rangegenerate_start")
for x in nodes:
    ver = x.parm("ver")
    path = x.path()
    name = x.name()
    if x.parm("extra"):
        name = name + x.parm("extra").eval()
```

```

else: pass
topcache = topnet.createNode("ropfetch")
p = hou.IntParmTemplate("version", "Version", 1)
g = topcache.parmTemplateGroup()
g.append(p)
topcache.setParmTemplateGroup(g)
topcache.parm("version").set(ver)
topcache.parm("roppath").set(path)
topcache.parm("framesperbatch").set(frb)
topcache.setName(name)

```

Send SOP to a ROP net named "ropnet1", adds version parm to update the original SOP version cache:

```

import hou
nodes = hou.selectedNodes()
ropnet = hou.node("/obj/ropnet1")
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    if x.type().name() == "rop_geometry":
        ver = x.parm("vp_version")
    elif x.type().name() == "rop_alembic":
        ver = x.parm("vp_version")
    else:
        ver = x.parm("version")
    topcache = ropnet.createNode("fetch")
    topcache.parm("source").set(path)
    p = hou.IntParmTemplate("version", "Version", 1)
    g = topcache.parmTemplateGroup()
    g.append(p)
    topcache.setParmTemplateGroup(g)
    topcache.parm("version").set(ver)
    topcache.setName(name)

```

Make a file node from a rop export node:

```

import hou, re
nodes = hou.selectedNodes()
parent = nodes[0].parent()
nodeList = []
for x in nodes:
    name = x.name()+"_load"

    version = x.parm("vp_version").eval()
    path= x.parm("sopoutput").eval()
    path = str(path)
    newpath1 = re.sub("_v\d+", "_v{0}", path).format("`padzero(3,ch('version'))`)")
    newpath1 = re.sub("\\.\\d+", ".$F4", newpath1)

    file = parent.createNode("file")
    try:
        file.setName(name)
    except:
        continue
    file.setColor(hou.Color(0,0,1))
    file.parm("file").set(newpath1)
    p = hou.IntParmTemplate("version", "Version", 1)
    g = file.parmTemplateGroup()
    g.append(p)
    file.setParmTemplateGroup(g)
    file.parm("version").set(version)
    nodeList.append(file)

parent.layoutChildren(items=nodeList)

```

Open Directory from Tops

```

import hou, re
nodes = hou.selectedNodes()

for x in nodes:
    rpath = x.parm("roppath").eval()

    try:

```

```

tnode = rpath.rpartition("/")[0]
dirpath = hou.node(tnode).parm("file").eval()
except:
    tnode = rpath
    dirpath = hou.node(tnode).parm("vp_path").eval()
    print(dirpath)
dirpath = dirpath.rpartition("/")[0]
hou.ui.showInFileBrowser(str(dirpath))

```

Get Alembic camera, import it, and link to other nodes:

```

import hou, os

#set parent network
network = hou.node("/obj")

#get shot number and cache directory
shot = os.getenv("SHOT")
shotcam = shot.split("/)[-1] + "_cam"
cache = os.getenv("CACHE") + "/layout/cam"

#get alembic file
getcampath = hou.ui.selectFile(cache, "SelectCamera", pattern="*.abc")
getcampath = hou.expandString(getcampath)

#make alembic node, set name, connect to SCALE node and add to CAMERA NODE
alnode = network.createNode("alembicarchive", shotcam)
alnode.parm("fileName").set(getcampath)
alnode.parm("buildHierarchy").pressButton()
alnode.setInput(0, hou.node("/obj/SCALE"))
hou.node("/obj/CAMERA").parm("CAMERA").set(f"/obj/{alnode}/CAM/CAMShape")

```

Selected node in obj level to an object merge:

```

node = hou.selectedNodes()
net = hou.node("/obj")
for x in node:
    name = x.name()
    makeout = net.createNode("geo")

```



```
makeout.setInput(0,x)
makeout.setName(name+"_INOUT")
makeout.moveToGoodPosition()
makeout.setColor(hou.Color(.5, .25, .6))
merge = makeout.createNode("object_merge")
merge.parm("objpath1").set(x.path())
```

Add timeshift with clamp after a cache node of a single frame (pipeline annoyance):

```
node = hou.selectedNodes()
for x in node:
    outnode = x.outputs()[0]
    name = x.name() + "_TIMESHIFT_clamp"
    start = x.parm("f1")
    end = x.parm("f2")
    net = x.parent()
    timeshift = net.createNode("timeshift")
    timeshift.parm("rangeclamp").set(3)
    timeshift.parm("frange1").deleteAllKeyframes()
    timeshift.parm("frange2").deleteAllKeyframes()
    timeshift.parm("frange1").set(start)
    timeshift.parm("frange2").set(end)
    timeshift.setName(name)
    timeshift.setInput(0, x)
    outnode.setInput(0, timeshift)
    timeshift.moveToGoodPosition()
```

Tops - range extend, sets the frame range by grabbing from selected cache nodes:

```
node = hou.selectedNodes()[0]
popup = hou.ui.selectNode(title="Select Node to grab range",node_type_filter=hou.nodeTypeFilter.Sop)

popup = hou.node(popup)
```

```

start = popup.parm("f1")
end = popup.parm("f2")

if node.type().name() == "rangeextend":
    node.parm("newrangex").set(start)
    node.parm("newrangey").set(end)
if node.type().name() == "rangegenerate":
    node.parm("rangex").set(start)
    node.parm("rangey").set(end)

```

Update Multiple Node Params at Once:

```

import hou

# Prompt for parameter name
parm_name = hou.ui.readInput("Parameter to change (e.g. 'uniformscale')", buttons=("OK", "Cancel"))[1]
if not parm_name:
    raise hou.Error("Parameter name not specified.")

# Prompt for value (literal or expression)
value_input = hou.ui.readInput(f"Value to set for '{parm_name}'\n(Prefix expressions with expr:)",
    buttons=("OK", "Cancel"))[1]
if not value_input:
    raise hou.Error("Value not specified.")

# Get selected nodes
selected_nodes = hou.selectedNodes()
if not selected_nodes:
    raise hou.Error("No nodes selected.")

# Check for expression prefix
is_expr = value_input.strip().startswith("expr:")
expr_str = value_input.strip()[5:].strip() if is_expr else value_input.strip()

# Apply to all selected nodes
for node in selected_nodes:
    parm = node.parm(parm_name)
    if not parm:
        print(f"Node '{node.name()}' does not have a parameter named '{parm_name}'")
        continue

```

```
try:
    if is_expr:
        parm.setExpression(expr_str, language=hcu.exprLanguage.Hscript)
    else:
        # Try float conversion first
        try:
            val = float(expr_str)
        except ValueError:
            val = expr_str
        parm.set(val)
except Exception as e:
    print(f"Failed to set value on '{node.name()}': {e}")
```

Python

PythonModule Scripts

Get houdini version:

```
hver = hou.applicationVersionString().rpartition('.')[0]
```

Move Files

```
import os,hou, shutil

selected = hou.selectedNodes()
for x in selected:
    if x.parm("env_map"):
        file = x.parm("env_map").eval()
        parm1 = x.parm("env_map")
    elif x.parm("fileName"):
        file = x.parm("fileName").eval()
        parm1 = x.parm("fileName")
    else:
        pass

filename = os.path.basename(file)
destdir = os.path.join(hou.expandString("$HIP"), "assets")
destpath = os.path.join(destdir, filename)
if os.path.exists(file):
    if os.path.exists(destdir):
        pass
    else:
        os.makedirs(destdir)

    if os.path.exists(destpath):
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)
    else:
        shutil.copy(file, destdir)
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)

else:import os,hou, shutil
selected = hou.selectedNodes()
for x in selected:
    if x.parm("env_map"):
        file = x.parm("env_map").eval()
```

```
    parm1 = x.parm("env_map")
elif x.parm("fileName"):
    file = x.parm("fileName").eval()
    parm1 = x.parm("fileName")
else:
    pass
filename = os.path.basename(file)
destdir = os.path.join(hou.expandString("$HIP"), "assets")
destpath = os.path.join(destdir, filename)
if os.path.exists(file):
    if os.path.exists(destdir):
        pass
    else:
        os.makedirs(destdir)

    if os.path.exists(destpath):
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)
    else:
        shutil.copy(file, destdir)
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)

else:
    pass
    pass
```

split by group

```
import hou

selected = hou.selectedNodes()[0]
groups = [g.name() for g in selected.geometry().primGroups()]

for i, name in enumerate(groups, 1):
    #make a split node
    split = selected.createOutputNode("blast")
    split.setName(name)
    split.parm("group").set(name)
    split.parm("negate").set(1)
    split.moveToGoodPosition()

for node in selected:
    out = node.createOutputNode("null")
    out.setName("OUT_" + node)
    out.moveToGoodPosition()
```

Update frame range from file

```
def grabFrames(self):
    import os
    plate = self.parm("backplate").eval()
    if not plate:
        framex = self.parm("frange1").eval()
        framey = self.parm("frange2").eval()
    else:
        flist = [x.split(".")[2] for x in os.listdir(os.path.dirname(plate))]
        fmin = min(flist)
        fmax = max(flist)
        self.parm("frange1").set(int(fmin))
        self.parm("frange2").set(fmax)
        framex = self.parm("frange1").eval()
        framey = self.parm("frange2").eval()

    hou.playbar.setFrameRange(framex, framey)
    hou.playbar.setPlaybackRange(framex, framey)
```


Python

OnCreated scripts

OnCreated Script to set name, color, shape of node:

```
cachename = hou.ui.readInput("Enter cache name")  
node = kwargs["node"]  
node.setName(cachename[1])  
node.setUserData('nodeshape', "tilted")  
node.setColor(hou.Color(1,0,0))
```

Bake Camera from Alembic

Shelf script to bake camera from Alembic camera in scene. Must select the child camera in the alembic sop.

```
import hou

obj = hou.node("/obj")

ocam = hou.node(hou.ui.selectNode(node_type_filter=houd.nodeTypeFilter.ObjCamera))
ver = ocam.parent().parent().parm("vpp_version_abc").eval().split("_")[-1]

reslist = ["1920x1080", "3840x2160", "3072x2109", "3024x2016", "2224x1548", "Keep Original", "Custom"]
sl = hou.ui.selectFromList(reslist, message="choose resolution", sort=True, exclusive=True)
stopval = sl[0]
resolution = reslist[stopval]
if resolution is "Keep Original":
    pass
elif resolution is "Custom":
    custom = hou.ui.readInput("Enter resolution as #x# format, ie: 1920x1080. The x is needed.", title="Enter Resolution")
    resolution = custom[1]
    ocam.parm("resx").set(resolution.split("x")[0])
    ocam.parm("resy").set(resolution.split("x")[1])

else:
    ocam.parm("resx").set(resolution.split("x")[0])
    ocam.parm("resy").set(resolution.split("x")[1])

try:
    shotinfo = hou.node("/obj/SHOTINFO")
    backplate = shotinfo.parm("backplate")
except:

    backplate = ocam.parm("vm_background")
```

pass

```
camName = ocam.name() + "_baked"
#setback = ocam.parm("vm_background").set(backplate)
tcam = obj.createNode("cam", camName)
tcam.moveToGoodPosition()
```

```
scalenull = obj.createNode("null", "shotscale")
scalenull.parm("scale").set(.1)
scalenull.moveToGoodPosition()
```

```
tcam.setInput(0, scalenull)
```

```
#add point with normal for facing cam normals
atwr = tcam.createNode("attribwrangle", "normal")
atwr.parm("snippet").set("v@N=set(0,0,1);")
atwr.setInput(0, tcam.node("camOrigin"))
normnull = tcam.createNode("null", "OUT_POINT")
normnull.setInput(0, atwr)
```

```
#copy keyframes
cam_xform=["tx", "ty", "tz", "rx", "ry", "rz"]
cam_parms=["resx", "resy", "aspect", "focal", "aperture", "orthowidth", "shutter", "focus", "fstop"]
tcam.parm("vm_background").set(backplate)
```

```
parms_bake = list()
parms_bake.extend(cam_xform)
parms_bake.extend(cam_parms)
start = hou.playbar.playbackRange()[0]
end = hou.playbar.playbackRange()[1]
```

```
p = hou.StringParmTemplate("version", "Version", 1)
g = tcam.parmTemplateGroup()
g.append(p)
tcam.setParmTemplateGroup(g)
tcam.parm("version").set(ver)
```

```
with hou.undos.group("bake cam"):
    for x in range(int(start), int(end + 1)):
```

```
hou.setFrame(x)
tcam.setWorldTransform(ocam.worldTransform())
for p in parms_bake:
    parm = tcam.parm(p)
    if parm.name() in cam_xform:
        parm.setKeyframe(hou.Keyframe(parm.eval()))
    else:
        parm.setKeyframe(hou.Keyframe(ocam.parm(p).eval()))
```

Python

Get frame range from alembic

This script should be added to a button on a node (thats why it's funnyily formated)

```
import _alembic_hom_extensions as ahe; import hou; anode = hou.pwd(); cam = anode.parm("camera").eval();  
fpath = hou.node(cam).parm("fileName"); ver = fpath.eval().split("_")[-1].split("/")[0]; print(ver); name =  
hou.node(cam).children() ; print(name[0]); anode.parm("cameraVer").set(ver); name = str(name[0]);  
anode.parm("cameraName").set(name); alembicpath= fpath.eval(); timerange =  
ahe.alembicTimeRange(alembicpath); start_time=timerange[0]*hou.fps(); end_time = timerange[1]*hou.fps();  
anode.setParms({"framemin":start_time, "framemax":end_time})
```

Example On Node Buttons

This is how a button on a non-adminned node needs to be laid out:

import hou (probably not needed) ; do something ;

This grabs frame range from supplied alembic camera, updates names, etc:

```
import _alembic_hom_extensions as ahe; import hou; anode = hou.pwd(); cam = anode.parm("camera").eval();
fpath = hou.node(cam).parm("fileName"); ver = fpath.eval().split("_")[-1].split("/")[0]; print(ver); name =
hou.node(cam).children() ; print(name[0]); anode.parm("cameraVer").set(ver); name = str(name[0]);
anode.parm("cameraName").set(name); alembicpath= fpath.eval(); timerange =
ahe.alembicTimeRange(alembicpath); start_time=timerange[0]*hou.fps(); end_time = timerange[1]*hou.fps();
anode.setParms({"framemin":start_time, "framemax":end_time})
```

This sets frame range from ranges on node:

```
import hou; anode = hou.pwd(); start = anode.parm("framemin").eval(); end = anode.parm("framemax").eval();
hou.playbar.setFrameRange(start, end); hou.playbar.setPlaybackRange(start, end)
```

This grabs info from animation alembic:

```
import hou; anode = hou.pwd(); anim = anode.parm("anim").eval(); fpath = hou.node(anim).parm("fileName");  
ver = fpath.eval().split("_")[-1].split("/")[0]; name = hou.node(anim) ; anode.parm("animVer").set(ver); name =  
str(name); anode.parm("animName").set(name);
```

oneliner for-loop -- updates name by index (not complete, need inputs):

```
i = 0; [cn.parm("name" + str(i := i + 1)).set(x.split("/")[-1]) for x in nodes]
```

Send to Tops

```
import hou

nodes = hou.selectedNodes()

topnet = hou.node("/obj/topnet1")

if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")

for x in nodes:
    name = x.name()+"_"+str(x.parent())
    fstart = x.parm("f1").eval()
    fend = x.parm("f2").eval()
    if x.type().name() == "rop_geometry":
        ver = x.parm("vp_version")
        path = x.path()
    elif x.type().name() == "rop_alembic":
        ver = x.parm("vp_version")
        path = x.path()
    elif x.type().name() == "filecache::2.0":
        path = x.path() + "/render"
        ver = x.parm("vp_version")
    else:
        ver = x.parm("version")
        path = x.path()

topcache = topnet.createNode("ropfetch")

try:
    if x.parm("cachesim").eval() is 1:
        topcache.parm("batchall").set(1)
        topcache.setColor(hou.Color(.5,0,0))
    else:
        topcache.parm("framesperbatch").set(15)
        topcache.setColor(hou.Color(0,.5,0))
```


except:

if x.parm("initsim").eval() is 1:

topcache.parm("batchall").set(1)

topcache.setColor(hou.Color(.5,0,0))

else:

topcache.parm("framesperbatch").set(15)

topcache.setColor(hou.Color(0,.5,0))

p = hou.IntParmTemplate("version", "Version", 1, min=1, max=40)

g = topcache.parmTemplateGroup()

g.insertAfter("pdg_servicename", p)

topcache.setParmTemplateGroup(g)

topcache.parm("version").set(ver)

topcache.parm("roppath").set(path)

topcache.setName(name)

Python

Set Frame Range without Script

```
import hou; anode = hou.pwd(); start = anode.parm("framemin").eval(); end = anode.parm("framemax").eval();  
hou.playbar.setFrameRange(start, end); hou.playbar.setPlaybackRange(start, end)
```

Python

ROP

PostRender open MPLAY:

```
import os; img_path = "`chs("picture")`.replace("$F", "\\*"); os.system("mplay %s" % img_path)
```

Python

Pull version from hipname

Can be used in a parameter. Returns a integer.

```
import hou, re
version = re.findall('_v\d+', hou.hipFile.basename())[0]
version = int(re.findall('\d+', version)[0])
return version
```

Python

Get Frame Size of Image File

```
node= hou.pwd(); bg=node.parm("image").eval(); res=hou.imageResolution(bg);  
node.parm("framesizex").set(res[0]); node.parm("framesizey").set(res[1]);
```

Create Agent from built in mocap rig - Simple

This will take a test mocap rig 3 built in to houdini, create an agent, add agent clips from the built in library (must be in your scene already), and lay everything out.

```
import hou

obj = hou.node("/obj")
agentname = hou.ui.readInput("Agent Name", title="Name")
agentname = agentname[1]

agentpNode = obj.createNode("geo")
agentNode = agentpNode.createNode("agent")

agentpNode.setName(agentname)
agentNode.setName(agentname)
agentnet = agentpNode

inputMoc = hou.ui.selectNode(title="Select Character Rig to base agent on", multiple_select=False,
node_type_filter=hou.nodeTypeFilter.ObjSubnet)

agentNode.parm("agentname").set(agentname)
agentNode.parm("objsubnet").set(inputMoc)

#clips = hou.ui.selectNode(multiple_select=True, node_type_filter=hou.nodeTypeFilter.Obj)
clips = hou.ui.selectNode(title="Select all clips - mocap biped 3 rigs", multiple_select=True,
node_type_filter=hou.nodeTypeFilter.ObjSubnet)
agentclip = agentnet.createNode("agentclip")
clipprops = agentnet.createNode("agentclipproperties")

clipnum = len(clips)
```

```
clipcount = 1
```

```
agentclip.parm("locomotionnode").set("Hips")
```

```
#print(clipnum)
```

```
for x in clips:
```

```
    node = hou.node(x)
```

```
    name = node.name()
```

```
    path = str(x)
```

```
    nframes = node.parm("nFrames")
```

```
    fs = hou.playbar.timelineRange()[0]
```

```
    fe = int(fs) + int(nframes.eval())
```

```
    agentclip.parm("framerange" + str(clipcount) + "_1").deleteAllKeyframes()
```

```
    agentclip.parm("framerange" + str(clipcount) + "_2").deleteAllKeyframes()
```

```
    agentclip.parm("clips").set(clipnum)
```

```
    agentclip.parm("name" + str(clipcount)).set(name)
```

```
    agentclip.parm("objsubnet" + str(clipcount)).set(path)
```

```
    agentclip.parm("framerange" + str(clipcount) + "_1").set(fs)
```

```
    agentclip.parm("framerange" + str(clipcount) + "_2").set(fe)
```

```
    agentclip.parm("converttoinplace" + str(clipcount)).set(True)
```

```
    clipprops.parm("numclips").set(clipnum)
```

```
    clipprops.parm("clipname_" + str(clipcount)).set(name)
```

```
    clipprops.parm("enableblending_" + str(clipcount)).set(True)
```

```
    clipprops.parm("framesbefore_" + str(clipcount)).set("5")
```

```
    clipprops.parm("framesafter_" + str(clipcount)).set("5")
```

```
clipcount = clipcount+1
```

```
agentclip.setFirstInput(agentNode)
```

```
clipprops.setFirstInput(agentclip)
```

```
agentpNode.layoutChildren()
```

Send selected nodes to new object (fancy way to create object merges)

```
import hou
nodes = hou.selectedNodes()
destnode = hou.node(hou.ui.selectNode(title="select destination node"))
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    objmergenode = destnode.createNode("object_merge")
    objmergenode.parm("objpath1").set(path)

    objmergenode.setName(name)
    objmergenode.setColor(hou.Color(0,1,0))
```


Send nodes to new alembic export

```
import hou

nodes = hou.selectedNodes()
destnode = hou.node("/obj/EXPORT")
if not destnode:
    destnode = hou.node("/obj").createNode("geo")
    destnode.setName("EXPORTS")

for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    objmergenode = destnode.createNode("object_merge")
    objmergenode.parm("objpath1").set(path)

    objmergenode.setName(name)
    objmergenode.setColor(hou.Color(0,1,0))

    alembicrop = destnode.createNode("rop_alembic")
    alembicrop.setName(str(x.parent()))
    alembicrop.parm("trange").set(1)
    alembicrop.parm("f1").deleteAllKeyframes()
    alembicrop.parm("f1").set(int("1001"))
    alembicrop.parm("build_from_path").set(1)
    alembicrop.setInput(0, objmergenode)
    destnode.layoutChildren()
```

Python

TOPs - symlink output file of parent

```
exportFile = str(work_item.expectedInputFiles[0])  
dir = os.path.dirname(exportFile)  
newFile = os.path.join(dir, "cache.abc")  
  
os.symlink(exportFile, newFile)
```

Copy Text to Clipboard example

This example I make a dictionary and copy to clipboard. I also gather a frame range from files on disk.

```
#needed: name, path, start, end
import hou, os
from pathlib import Path

def getinfo():
    pathname = hou.ui.selectFile(collapse_sequences=True)
    filename = Path(pathname.split(".")[0])
    parent = filename.parent

    #get frame range
    filenames = [file.name.split(".")[2] for file in parent.iterdir() if file.is_file()]
    start = min(int(i) for i in filenames)
    end = max(int(i) for i in filenames)

    #reformatting stuff
    name = str(filename).split("/)[-1]
    path = str(filename)+". "

    return name, path, start, end

def wrangle():
    wranglenode = hou.selectedNodes[0]
    #assign variables to function so we can use them globally
    name, path, start, end = getinfo()

    #format stuff
    q = ""
```

```
textForWrangle = f'dict {name}; \n {name}[\\"name\\"] = {q}{name}{q}; \n {name}[\\"path\\"] = {q}{path}{q};  
\n {name}[\\"startFrame\\"] = {start}; \n {name}[\\"endFrame\\"] = {end}; \n append(chars,{name}); '  
print(textForWrangle)  
#copy to clipboard  
hou.ui.copyTextToClipboard(textForWrangle)  
  
hou.ui.displayMessage(title="Copied", text=f"Here is what was copied to clipboard: {textForWrangle} \n")
```

Button Python Scripts

Make Flipbook button. Must make an opengl in pipeline for the path details. Takes resolution from camera in ShotInfo node.

```
import hou, re, os; stealfile =hou.ui.selectNode(title="Select OpenGL Export Node to steal path from",
multiple_select=False, node_type_filter=hou.nodeTypeFilter.Rop); filepath =
hou.node(stealfile).parm("vp_path").eval(); renderpath = re.sub(r'\\.d+\\.','.$F4.', filepath); confirm=
hou.ui.displayMessage(f"this path cool? {renderpath}", buttons=('Yes', 'No, abort'), default_choice=0); frames =
hou.playbar.frameRange(); shotinfo = hou.pwd(); resx = shotinfo.parm("fs3x").eval(); resy =
shotinfo.parm("fs3y").eval(); exit() if confirm == 1 else None; cur_desktop = hou.ui.curDesktop(); scene_viewer
= hou.paneTabType.SceneViewer; scene = cur_desktop.paneTabOfType(scene_viewer);
scene.flipbookSettings().stash(); flip_book_options = scene.flipbookSettings();
flip_book_options.output(renderpath); flip_book_options.frameRange((frames[0],
frames[1]));flip_book_options.useResolution(1); print(int(resx));flip_book_options.resolution((int(resx), int(resy)));
scene.flipbook(scene.curViewport(), flip_book_options)
```

Get and Set properties on ShotInfo node (null)

```
import os; node = hou.pwd(); scenescale = node.evalParm("scenescale"); alter=hou.ui.selectNode(title="Which
nodes to set scale?", multiple_select=True, node_type_filter=hou.nodeTypeFilter.ObjGeometry);
[hou.node(x).parm("scale2").set(scenescale) for x in (alter or []) if x is not None]; shotresx = os.environ["RX"];
shotresy = os.environ["RY"]; node.parm("fsx").set(shotresx); node.parm("fsy").set(shotresy); cam =
node.evalParm("cam") ; cam = node.node(cam); cam = cam.path() ; cam = hou.node(cam); parent =
cam.input(0); parent.parm("camera_scale").set(scenescale); ver = parent.parm("vpp_version_cam").eval();
node.parm("camver").set(ver.split("_")[-1]); parent.parm("plate_0").set(node.parm("back").unexpandedString());
camrx = node.parm("fs3x").eval(); camry = node.parm("fs3y").eval(); cam.parm("resx").set(camrx);
cam.parm("resy").set(camry);
```

Python

Tops Random

Get the range from a range gen or extend -- works on items:

```
pdgattrib("range", 0) #first frame  
pdgattrib("range", 1) #last frame
```

TOPS mplay python

```
import subprocess
import os

def onGenerate(work_item):
    # Get the parent graph
    parent = work_item.parentItemHolder

    # Collect output file paths from upstream items
    all_inputs = parent.inputItems
    file_paths = []

    for item in all_inputs:
        # Adjust 'file' if your attribute is named differently
        path = item.attrbValue('file')
        if path and os.path.exists(path):
            file_paths.append(path)

    if file_paths:
        # Launch mplay with all the output files
        subprocess.Popen(["mplay"] + file_paths)
    else:
        print("No valid flipbook files found.")

    return True
```

VEX

VEX

Camera Stuff

auto focus, get distance from object and camera:

```
vlength(vtorigin("/obj/geo1", "/obj/cam1"))
```

Points

divide points into 3 equal parts:

```
i@part = floor(fit(rand(@ptnum+.258), 0, 1, 0, 2.9));
```

Nage replacement

```
@nage = fit(@age,0,@life,0,1);
```

Group from class:

```
string grpname = sprintf("class_%d", i@class);
setprimgroup(0, grpname, @primnum, 1); // use setpointgroup() if running over points
```

Connect close points:

```
float max_dist = chf("connect_distance");

int npts = @numpt;
for (int i = 0; i < npts; i++) {
    vector pi = point(0, "P", i);
    for (int j = i+1; j < npts; j++) {
        vector pj = point(0, "P", j);
        if (distance(pi, pj) < max_dist) {
            int prim = addprim(0, "polyline");
            addvertex(0, prim, i);
            addvertex(0, prim, j);
            setprimattrib(0, "create_frame", prim, @Frame);
        }
    }
}
```

Shift 0 -1 to 0 - 1 - 0:

```
float mask = f@mask;

float midpoint = 0.5;

float result = 1.0 - abs(mask - midpoint) * 2.0;
result = clamp(result, 0.0, 1.0);

f@newmask = result;
```

Confine points to sphere:

```
vector center = prim(1, "P", 0);
float radius = ch("scale");

vector dir = @P - center;
float dist = length(dir);

if (dist > radius) {
    @P = center + normalize(dir) * radius;
}
```

Connect points with lines by dist:

```
float max_dist = chf("connect_distance");

// Loop through all points in Group A
int npts = @numpt;
for (int i = 0; i < npts; i++) {
    if (!inpointgroup(0, "groupA", i)) continue;

    vector pi = point(0, "P", i);

    // Loop through all points in Group B
    for (int j = 0; j < npts; j++) {
        if (!inpointgroup(0, "groupB", j)) continue;

        // Avoid self-connection in case of overlapping group membership
        if (i == j) continue;
```

```
vector pj = point(0, "P", j);
```

```
if (distance(pi, pj) < max_dist) {
```

```
    int prim = addprim(0, "polyline");
```

```
    addvertex(0, prim, i);
```

```
    addvertex(0, prim, j);
```

```
    @primid = @primnum;
```

```
}
```

```
}
```

```
}
```

VEX

If then statements

If the pscale is greater than .4 then set it to .2, if not set it to its current pscale

```
@pscale = @pscale>.4?.2:@pscale
```

Transforms and Junk

1. transforms to attribute matrix:

```
p@orient = quaternion(3@transform);
v@scale = cracktransform(0,0,2,set(0.0.0). 3@transform);
```

2. rotate packed fracture based on point + distance:

Screenshot from 2023-06-21 11-48-58.png

```
vector p1= set(@P.x, @P.y, @P.z);

vector crack1 = point(1, "P", 0);
vector crack2 = point(2, "P", 0);
vector p2 = crack1-p1;
vector p3 = crack2-p1;

float n = fit ( length ( p2 ), 0, ch("maxdist"), ch('mult'), 0 );
float n2 = fit ( length ( p3 ), 0, ch("maxdist2"), ch('mult2'), 0 );

vector4 q0 = quaternion ( 0 );
vector4 q1 = sample_orientation_uniform ( rand ( @ptnum ) );
vector4 q2 = slerp ( q0, q1, n+n2 );
matrix3 xform = qconvert ( q2 );

setprimintrinsic ( 0, "transform", @ptnum, xform );
```

3. Blending spiral (end beg):

Screenshot from 2023-06-21 15-48-58.png

```
vector target = point(1, "P", @ptnum);
float blend = chramp("blendAlongSpiral", @curveu)*chf("multiplier");

@P = lerp(@P, target, blend);
```

4. Position copy via uv:

Screenshot from 2023-06-21 15-51-53.png

```
v@P = uvsample(1, "P", "uv", @P);
```

5. move near points together:

```
int near = nearpoint(1, @P);  
vector target = point(1, "P", near);  
@P = target;
```

6. Affect the scale of packed prims:

```
//vector scale = fit01(vector(rand(@primnum)), 0,1.46) *@growth;  
vector scale = ch("scale");  
  
matrix3 trn = primintrinsic(0, "transform", @primnum);  
matrix scalem = maketransform(0, 0, {0,0,0}, {0,0,0}, scale, @P);  
trn *= matrix3(scalem);  
setprimintrinsic(0, "transform", @primnum, trn);
```

Orientation

Get transform and orientation from camera:

```
string camera = "/obj/alembicarchive1/Camera2/CameraShape2"; // path to your camera
@P = ptransform(camera, "space:current", {0,0,0});
@N = ntransform(camera, "space:current", {0,0,-1});
```

Random orient on points:

```
float seed = float(@ptnum);
vector4 orient = quaternion(radians(rand(seed) * ch("add")), normalize(rand(seed + 1)));
@orient = orient;
```

Point normals at camera:

```
string cam = chs("cam");
matrix cam_xform = optransform(cam);
vector dirtocam = cracktransform(0,0,0,{0,0,0}, cam_xform);
@N = normalize(dirtocam - @P);
```


Spiral

```
#include "math.h"
#include "voplib.h"

float easeOutCirc ( float t )
{
    return sqrt ( 1 - ( pow ( ( 1 - t ), 2 ) ) );
}

float index = @ptnum;
float numpts = @numpt;
float startAngle = radians ( ch("angle") );
float dir = 2 * ch("dir") - 1;
float steps = ( numpts - 1 ) / ch("turns");
float stepAngle = ( 2 * PI / steps ) * dir;

float inc = index / ( numpts - 1 );
int mirror = chi("spherical");
float linear = ( 1 + mirror ) * inc;
if ( mirror && index + 1 > numpts / 2 )
    linear = ( 1 + mirror ) * ( 1 - inc );

float circ = easeOutCirc ( linear );
float interp = linear + ( circ - linear ) * ch("roundness");
float r = ( ch("rx") + interp * ( ch("ry") - ch("rx") ) );

// Apply power to radius at the end (after curvature)
inc = ( ( numpts - 1 ) - index ) / ( numpts - 1 );
float theta = 2 * PI * inc;
if ( mirror && index + 1 > numpts / 2 )
    theta = 2 * PI * ( 1 - inc );
r *= pow ( ch("falloff"), theta );

float angle = index * stepAngle + startAngle;
```

```
float x = sin ( angle ) * r;  
float z = cos ( angle ) * r;  
float h = index / ( numpts - 1 );  
float y = vop_bias ( h, 0.5 * ch("bias") + 0.5 );  
y = vop_gain ( y, 0.5 * ch("gain") + 0.5 ) * ch("height");  
  
matrix3 xform = dihedral ( { 0, 1, 0 }, { 0, 0, -1 } ) * lookat ( 0, normalize ( chv("n") ) );  
@P = ch("scale") * set ( x, y, z ) * xform + chv("t");
```

VEX

Links

Big resource:

<https://lex.ikoon.cz/vex-snippets/>

Comparing array

Find the difference between input 1's ids and input 0's:

```
int delete_ids[] = array();

int numPrims = nprimitives(1);
for (int i = 0; i < numPrims; i++) {
    int leaf_id = prim(1, "leafid", i);
    append(delete_ids, leaf_id);
}

int my_id = i@leafid;

if (find(delete_ids, my_id) >= 0) {
    @group_keep=1;
}
```

Looping

Loop moving points on curve using CurveU:

```
int loop_frames = chi("loop_frame");
float fps = 29.97;
float loop_time = loop_frames / fps;

float t = @Time / loop_time;
t -= floor(t);

float ping = abs(2 * t - 1);
float speed_mult = chf("speed_mult");
ping *= speed_mult;

float exponent = chf("ease_exponent");
float slow_ping = pow(ping, exponent);

float u = f@curveu + slow_ping;
u -= floor(u);

int prim = i@class;
vector pos = primuv(1, "P", prim, set(u, 0, 0));
@P = pos;
```

Add a resample node with curveu, also to control amount of points

Loop points in Y:

```
int loop_frames = chi("loop_frames");
float fps = 29.97;
```

```
float loop_time = loop_frames / fps;

float t = @Time / loop_time;
t -= floor(t);

float offset = frac(t + rand(@ptnum)); // unique phase per point

float min_y = chf("min_y");
float max_y = chf("max_y");
float range = max_y - min_y;

@P.y = min_y + offset * range;
```

Loop on CurveU (nonPingPong):

1st attribute wrangle set to points after the point scatter:

```
vector uvw;
int prim;
float dist = xyzdist(1, @P, prim, uvw);
f@curveu = uvw.x;
i@class = prim;
```

2nd attrib wrangle set to points one the 1st input as the points and the 2nd to the curve with curevu from resample:

```
int loop_frames = chi("loop_frames");
float fps = 29.97;
float loop_time = loop_frames / fps;
//get time
float t = @Time / loop_time;
t -= floor(t);
```

```
float speed = chf("speed");

// offset
float base_u = f@curveu;
float offset_u = t * speed;

float u = base_u + offset_u;
u -= floor(u); // wrap it around

int prim = i@class;
vector pos = primuv(1, "P", prim, set(u, 0, 0));
@P = pos;
```

Expressions

Switch by Normal:

```
if(point("../resample3", 0, "N", 2)<0, 0, 1)
```


My Shelf Setup XML

My shelf tools setup, in progress. Save to houdinixx.x/toolbar/daam.shelf

```
<?xml version="1.0" encoding="UTF-8"?>
<shelfDocument>
  <!-- This file contains definitions of shelves, toolbars, and tools.
  It should not be hand-edited when it is being used by the application.
  Note, that two definitions of the same element are not allowed in
  a single file. -->

  <toolshelf name="daam" label="daam">
    <memberTool name="SopToTops"/>
    <memberTool name="rop_to_top"/>
    <memberTool name="TOPS_rangeselect"/>
    <memberTool name="versionup"/>
    <memberTool name="nodeVersionDown"/>
    <memberTool name="sop_makeFile"/>
    <memberTool name="showfile"/>
    <memberTool name="exportToNew"/>
    <memberTool name="sopTimeClamp"/>
    <memberTool name="Flipbook"/>
    <memberTool name="ChangeMulti"/>
  </toolshelf>

  <tool name="SopToTops" label="SOPtoTOP" icon="hicon:/SVGIcons.index?COP2_subnet.svg">
    <script scriptType="python"><![CDATA[import hou
nodes = hou.selectedNodes()
topnet = hou.node("/obj/topnet1")
if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    fstart = x.parm("f1").eval()
    fend = x.parm("f2").eval()
    if x.type().name() == "rop_geometry":
```

```

    ver = x.parm("vp_version")
    path = x.path()
elif x.type().name() == "rop_alembic":
    ver = x.parm("vp_version")
    path = x.path()
elif x.type().name() == "filecache::2.0":
    path = x.path() + "/render"
    ver = x.parm("vp_version")
else:
    ver = x.parm("version")
    path = x.path()

```

```

topcache = topnet.createNode("ropfetch")

```

```

try:

```

```

    if x.parm("cachesim").eval() is 1:
        topcache.parm("batchall").set(1)
        topcache.setColor(hou.Color(.5,0,0))
    else:
        topcache.parm("framesperbatch").set(15)
        topcache.setColor(hou.Color(0,.5,0))

```

```

except:

```

```

    if x.parm("initsim").eval() is 1:
        topcache.parm("batchall").set(1)
        topcache.setColor(hou.Color(.5,0,0))
    else:
        topcache.parm("framesperbatch").set(15)
        topcache.setColor(hou.Color(0,.5,0))

```

```

p = hou.IntParmTemplate("version", "Version", 1, min=1, max=40)

```

```

g = topcache.parmTemplateGroup()

```

```

g.insertAfter("pdg_servicename", p)

```

```

topcache.setParmTemplateGroup(g)

```

```

topcache.parm("version").set(ver)

```

```

topcache.parm("roppath").set(path)

```

```

topcache.setName(name)]]></script>

```

```

</tool>

```

```

<tool name="TOPS_rangeselect" label="TOPS RangeSelect"

```

```

icon="hicon:/SVGIcons.index?BUTTONS_set_framerange.svg">

```

```

    <script scriptType="python"><![CDATA[node = hou.selectedNodes()[0]

```

```

    popup = hou.ui.selectNode(title="Select Node to grab range",node_type_filter=hou.nodeTypeFilter.Sop)

```

```
popup = hou.node(popup)
start = popup.parm("f1")
end = popup.parm("f2")
start.deleteAllKeyframes();
end.deleteAllKeyframes();
```

```
if node.type().name() == "rangeextend":
    node.parm("newrangex").set(start)
    node.parm("newrangey").set(end)
if node.type().name() == "rangegenerate":
    node.parm("rangex").set(start)
    node.parm("rangey").set(end)]]></script>
</tool>
```

```
<tool name="versionup" label="Node Version UP" icon="hicon:/SVGIcons.index?BUTTONS_up.svg">
    <script scriptType="python"><![CDATA[import hou
nodes = hou.selectedNodes()
for x in nodes:
    try:
        ver = x.parm("vp_version").eval() + 1
    except:
        ver = x.parm("version").eval() + 1
    x.parm("version").set(ver)]]></script>
</tool>
```

```
<tool name="rop_to_top" label="ROPtO TOP" icon="hicon:/SVGIcons.index?CHOP_reorder.svg">
    <script scriptType="python"><![CDATA[import hou
nodes = hou.selectedNodes()
topnet = hou.node("/obj/topnet1")
frb = round((hou.playbar.frameRange()[1] - hou.playbar.frameRange()[0]) / 2)

if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")
if not hou.node("/obj/topnet1/rangegenerate_start"):
    rg = topnet.createNode("rangegenerate")
    rg.setName("rangegenerate_start")
for x in nodes:
    ver = x.parm("vp_version")
```

```

path = x.path()
name = x.name()
if x.parm("extra"):
    name = name + x.parm("extra").eval()
else: pass
topcache = topnet.createNode("ropfetch")
topcache.setColor(hou.Color(0,0,0))
topcache.setUserData("nodeshape", "circle")
p = hou.IntParmTemplate("version", "Version", 1)
g = topcache.parmTemplateGroup()
g.append(p)
topcache.setParmTemplateGroup(g)
topcache.parm("version").set(ver)
topcache.parm("roppath").set(path)
topcache.parm("framesperbatch").set(frb)
topcache.setName(name)]]></script>
</tool>

```

```

<tool name="sop_makeFile" label="SOP makeFile From ROP"
icon="hicon:/SVGIcons.index?BUTTONS_upload.svg">
    <script scriptType="python"><![CDATA[import hou, re
nodes = hou.selectedNodes()
parent = nodes[0].parent()
nodeList = []
for x in nodes:
    name = x.name()+"_load"

    version = x.parm("vp_version").eval()
    path= x.parm("sopoutput").eval()
    path = str(path)
    newpath1 = re.sub("_v\d+", "_v{0}", path).format("`padzero(3,ch('version'))`)")
    newpath1 = re.sub("\.d+", ".$F4", newpath1)

    file = parent.createNode("file")
    try:
        file.setName(name)
    except:
        continue
    file.setColor(hou.Color(0,0,1))

```

```
file.parm("file").set(newpath1)
p = hou.IntParmTemplate("version", "Version", 1)
g = file.parmTemplateGroup()
g.append(p)
file.setParmTemplateGroup(g)
file.parm("version").set(version)
nodeList.append(file)
```

```
parent.layoutChildren(items=nodeList)]]></script>
</tool>
```

```
<tool name="showfile" label="TOPS Show File in Nautilus"
icon="hicon:/SVGIcons.index?BUTTONS_addassetdirectory.svg">
  <script scriptType="python"><![CDATA[import hou, re
nodes = hou.selectedNodes()
```

```
for x in nodes:
    rpath = x.parm("roppath").eval()

    try:
        tnode = rpath.rpartition("/")[0]
        dirpath = hou.node(tnode).parm("file").eval()
    except:
        tnode = rpath
        dirpath = hou.node(tnode).parm("vp_path").eval()
        print(dirpath)
    dirpath = dirpath.rpartition("/")[0]
    hou.ui.showInFileBrowser(str(dirpath))]]></script>
</tool>
```

```
<tool name="exportToNew" label="SOP send to new" icon="hicon:/SVGIcons.index?BUTTONS_cut.svg">
  <script scriptType="python"><![CDATA[node = hou.selectedNodes()
net = hou.node("/obj")
for x in node:
    name = x.name()
    makeout = net.createNode("geo")
    makeout.setInput(0,x)
    makeout.setName(name+"_INOUT")
    makeout.moveToGoodPosition()
    makeout.setColor(hou.Color(.5, .25, .6))
```

```
merge = makeout.createNode("object_merge")
merge.parm("objpath1").set(x.path())]]></script>
</tool>
```

```
<tool name="sopTimeClamp" label="SOP time clamp" icon="hicon:/SVGIcons.index?SOP_timeblend.svg">
  <script scriptType="python"><![CDATA[node = hou.selectedNodes()
for x in node:
  outnode = x.outputs()[0]
  name = x.name() + "_TIMESHIFT_clamp"
  start = x.parm("f1")
  end = x.parm("f2")
  net = x.parent()
  timeshift = net.createNode("timeshift")
  timeshift.parm("rangeclamp").set(3)
  timeshift.parm("frange1").deleteAllKeyframes()
  timeshift.parm("frange2").deleteAllKeyframes()
  timeshift.parm("frange1").set(start)
  timeshift.parm("frange2").set(end)
  timeshift.setName(name)
  timeshift.setInput(0, x)
  outnode.setInput(0, timeshift)
  timeshift.moveToGoodPosition()]]></script>
</tool>
```

```
<tool name="nodeVersionDown" label="Node Version DOWN"
icon="hicon:/SVGIcons.index?BUTTONS_down.svg">
  <script scriptType="python"><![CDATA[import hou
nodes = hou.selectedNodes()
for x in nodes:
  ver = x.parm("version").eval() -1
  x.parm("version").set(ver)]]></script>
</tool>
```

```
<tool name="Flipbook" label="Flipbook" icon="hicon:/SVGIcons.index?BUTTONS_capture.svg">
  <script scriptType="python"><![CDATA[import hou
import re

def flipbook_from_node():
  try:
    # Ask user to pick a ROP node to steal the path from
```

```

stealfile = hou.ui.selectNode(
    title="Select OpenGL Export Node to steal path from",
    multiple_select=False,
    node_type_filter=hou.nodeTypeFilter.Rop
)
if not stealfile:
    return

# Get the output path and convert to $F4 format
filepath = hou.node(stealfile).parm("vp_path").eval()
renderpath = re.sub(r'\.\d+\.', '.$F4.', filepath)

# Confirm the output path
confirm = hou.ui.displayMessage(
    f"Use this path?\n\n{renderpath}",
    buttons=('Yes', 'No'),
    default_choice=0
)
if confirm != 0:
    return

# Resolution preset options
resolution_presets = [
    "1920x1080", # Default
    "1280x720",
    "2048x858",
    "3840x2160",
    "Custom"
]

# Ask user to select resolution preset
choice = hou.ui.selectFromList(
    resolution_presets,
    message="Select Flipbook Resolution",
    title="Resolution Presets",
    exclusive=True,
    default_choices=[0]
)

if not choice:

```

```
return
```

```
selection = resolution_presets[choice[0]]
```

```
if selection == "Custom":
```

```
    # Ask for custom resolution
```

```
    resx_str = hou.ui.readInput("Enter custom resolution X:", buttons=("OK",), close_choice=0)[1]
```

```
    resy_str = hou.ui.readInput("Enter custom resolution Y:", buttons=("OK",), close_choice=0)[1]
```

```
    resx = int(resx_str)
```

```
    resy = int(resy_str)
```

```
else:
```

```
    resx, resy = map(int, selection.split("x"))
```

```
# Get current frame range
```

```
frames = hou.playbar.frameRange()
```

```
# Setup the flipbook
```

```
cur_desktop = hou.ui.curDesktop()
```

```
scene = cur_desktop.paneTabOfType(hou.paneTabType.SceneViewer)
```

```
if not scene:
```

```
    hou.ui.displayMessage("No Scene Viewer found.")
```

```
    return
```

```
scene.flipbookSettings().stash()
```

```
flipbook_options = scene.flipbookSettings()
```

```
flipbook_options.output(renderpath)
```

```
flipbook_options.frameRange((frames[0], frames[1]))
```

```
flipbook_options.useResolution(True)
```

```
flipbook_options.resolution((resx, resy))
```

```
# Run the flipbook
```

```
scene.flipbook(scene.curViewport(), flipbook_options)
```

```
except Exception as e:
```

```
    hou.ui.displayMessage(f"Error: {str(e)}")
```

```
# Run it
```

```
flipbook_from_node()]]></script>
```

```
</tool>
```



```

<tool name="ChangeMulti" label="ChangeMultiParm"
icon="hicon:/SVGIcons.index?BUTTONS_pdg_task_table.svg">
  <script scriptType="python"><![CDATA[import hou

# Prompt for parameter name
parm_name = hou.ui.readInput("Parameter to change (e.g. 'uniformscale')", buttons=("OK", "Cancel"))[1]
if not parm_name:
    raise hou.Error("Parameter name not specified.")

# Prompt for value (literal or expression)
value_input = hou.ui.readInput(f"Value to set for '{parm_name}'\n(Prefix expressions with expr:)",
buttons=("OK", "Cancel"))[1]
if not value_input:
    raise hou.Error("Value not specified.")

# Get selected nodes
selected_nodes = hou.selectedNodes()
if not selected_nodes:
    raise hou.Error("No nodes selected.")

# Check for expression prefix
is_expr = value_input.strip().startswith("expr:")
expr_str = value_input.strip()[5:].strip() if is_expr else value_input.strip()

# Apply to all selected nodes
for node in selected_nodes:
    parm = node.parm(parm_name)
    if not parm:
        print(f"Node '{node.name()}' does not have a parameter named '{parm_name}'")
        continue

    try:
        if is_expr:
            parm.setExpression(expr_str, language=houd.exprLanguage.Hscript)
        else:
            # Try float conversion first
            try:
                val = float(expr_str)
            except ValueError:

```

```
        val = expr_str
    parm.set(val)
except Exception as e:
    print(f"Failed to set value on '{node.name()}': {e}")
]]></script>
</tool>
```

```
<shelfSetEdit name="shelf_set_1" fileLocation="/mnt/jobs/software/houdini/hfs20.5.370-
py310/houdini/toolbar/ShelfDefinitions.shelf">
    <addMemberToolshelf name="NOISE" inPosition="14"/>
    <addMemberToolshelf name="daam" inPosition="15"/>
</shelfSetEdit>
</shelfDocument>
```

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