

# Python

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# Fun Shelf Scripts

Version up sops that have a "version" parm - I use this to version up a lot of exports in tops or rops:

```
import hou
nodes = hou.selectedNodes()
for x in nodes:
    ver = x.parm("version").eval() + 1
    x.parm("version").set(ver)
```

Send a ROP fetch to TOPs name "topnet1" for convenient cooking.:

```
import hou
nodes = hou.selectedNodes()
topnet = hou.node("/obj/topnet1")
frb = round((hou.playbar.frameRange()[1] - hou.playbar.frameRange()[0]) / 2)

if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")
if not hou.node("/obj/topnet1/rangegenerate_start"):
    rg = topnet.createNode("rangegenerate")
    rg.setName("rangegenerate_start")
for x in nodes:
    ver = x.parm("ver")
    path = x.path()
    name = x.name()
    if x.parm("extra"):
        name = name + x.parm("extra").eval()
    else: pass
    topcache = topnet.createNode("ropfetch")
```

```
p = hou.IntParmTemplate("version", "Version", 1)
g = topcache.parmTemplateGroup()
g.append(p)
topcache.setParmTemplateGroup(g)
topcache.parm("version").set(ver)
topcache.parm("roppath").set(path)
topcache.parm("framesperbatch").set(frb)
topcache.setName(name)
```

Send SOP to a ROP net named "ropnet1", adds version parm to update the original SOP version cache:

```
import hou
nodes = hou.selectedNodes()
ropnet = hou.node("/obj/ropnet1")
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    if x.type().name() == "rop_geometry":
        ver = x.parm("vp_version")
    elif x.type().name() == "rop_alembic":
        ver = x.parm("vp_version")
    else:
        ver = x.parm("version")
    topcache = ropnet.createNode("fetch")
    topcache.parm("source").set(path)
    p = hou.IntParmTemplate("version", "Version", 1)
    g = topcache.parmTemplateGroup()
    g.append(p)
    topcache.setParmTemplateGroup(g)
    topcache.parm("version").set(ver)
    topcache.setName(name)
```

Make a file node from a rop export node:

```

import hou, re
nodes = hou.selectedNodes()
parent = nodes[0].parent()
nodeList = []
for x in nodes:
    name = x.name()+"_load"

    version = x.parm("vp_version").eval()
    path= x.parm("sopoutput").eval()
    path = str(path)
    newpath1 = re.sub("_v\d+", "_v{0}", path).format("`padzero(3,ch('version'))`)")
    newpath1 = re.sub("\\.d+", ".$F4", newpath1)

    file = parent.createNode("file")
    try:
        file.setName(name)
    except:
        continue
    file.setColor(hou.Color(0,0,1))
    file.parm("file").set(newpath1)
    p = hou.IntParmTemplate("version", "Version", 1)
    g = file.parmTemplateGroup()
    g.append(p)
    file.setParmTemplateGroup(g)
    file.parm("version").set(version)
    nodeList.append(file)

parent.layoutChildren(items=nodeList)

```

## Open Directory from Tops

```

import hou, re
nodes = hou.selectedNodes()

for x in nodes:
    rpath = x.parm("roppath").eval()
    tnode = rpath.rpartition("/")[0]
    dirpath = hou.node(tnode).parm("file").eval()
    dirpath = dirpath.rpartition("/")[0]

```

```
hou.ui.showInFileBrowser(str(dirpath))
```

## Get Alembic camera, import it, and link to other nodes:

```
import hou, os

#set parent network
network = hou.node("/obj")

#get shot number and cache directory
shot = os.getenv("SHOT")
shotcam = shot.split("/")[-1] + "_cam"
cache = os.getenv("CACHE") + "/layout/cam"

#get alembic file
getcampath = hou.ui.selectFile(cache, "SelectCamera", pattern="*.abc")
getcampath = hou.expandString(getcampath)

#make alembic node, set name, connect to SCALE node and add to CAMERA NODE
alnode = network.createNode("alembicarchive", shotcam)
alnode.parm("fileName").set(getcampath)
alnode.parm("buildHierarchy").pressButton()
alnode.setInput(0, hou.node("/obj/SCALE"))
hou.node("/obj/CAMERA").parm("CAMERA").set(f"/obj/{alnode}/CAM/CAMShape")
```

# PythonModule Scripts

Get houdini version:

```
hver = hou.applicationVersionString().rpartition('.')[0]
```

# Move Files

```
import os,hou, shutil

selected = hou.selectedNodes()
for x in selected:
    if x.parm("env_map"):
        file = x.parm("env_map").eval()
        parm1 = x.parm("env_map")
    elif x.parm("fileName"):
        file = x.parm("fileName").eval()
        parm1 = x.parm("fileName")
    else:
        pass
    filename = os.path.basename(file)
    destdir = os.path.join(hou.expandString("$HIP"), "assets")
    destpath = os.path.join(destdir, filename)
    if os.path.exists(file):
        if os.path.exists(destdir):
            pass
        else:
            os.makedirs(destdir)

        if os.path.exists(destpath):
            dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
            parm1.set(dpath)
        else:
            shutil.copy(file, destdir)
            dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
            parm1.set(dpath)

else:import os,hou, shutil
selected = hou.selectedNodes()
for x in selected:
    if x.parm("env_map"):
        file = x.parm("env_map").eval()
        parm1 = x.parm("env_map")
    elif x.parm("fileName"):
```

```
file = x.parm("fileName").eval()
parm1 = x.parm("fileName")
else:
    pass
filename = os.path.basename(file)
destdir = os.path.join(hou.expandString("$HIP"), "assets")
destpath = os.path.join(destdir, filename)
if os.path.exists(file):
    if os.path.exists(destdir):
        pass
    else:
        os.makedirs(destdir)

    if os.path.exists(destpath):
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)
    else:
        shutil.copy(file, destdir)
        dpath = os.path.join(os.path.join("$HIP", "assets"), filename)
        parm1.set(dpath)

else:
    pass
    pass
```



# split by group

```
import hou

selected = hou.selectedNodes()[0]
groups = [g.name() for g in selected.geometry().primGroups()]
for i, name in enumerate(groups, 1):
    #make a split node
    split = selected.createOutputNode("blast")
    split.setName(name)
    split.parm("group").set(name)
    split.parm("negate").set(1)
    split.moveToGoodPosition()

for node in selected:
    out = node.createOutputNode("null")
    out.setName("OUT_" + node)
    out.moveToGoodPosition()
```

# Update frame range from file

```
def grabFrames(self):  
    import os  
    plate = self.parm("backplate").eval()  
    if not plate:  
        framex = self.parm("frange1").eval()  
        framey = self.parm("frange2").eval()  
    else:  
        flist = [x.split(".")[2] for x in os.listdir(os.path.dirname(plate))]  
        fmin = min(flist)  
        fmax = max(flist)  
        self.parm("frange1").set(int(fmin))  
        self.parm("frange2").set(fmax)  
        framex = self.parm("frange1").eval()  
        framey = self.parm("frange2").eval()  
  
    hou.playbar.setFrameRange(framex, framey)  
    hou.playbar.setPlaybackRange(framex, framey)
```

# OnCreated scripts

## OnCreated Script to set name, color, shape of node:

```
cachename = hou.ui.readInput("Enter cache name")
```

```
node = kwargs["node"]
```

```
node.setName(cachename[1])
```

```
node.setUserData('nodeshape', "tilted")
```

```
node.setColor(hou.Color(1,0,0))
```

# Bake Camera from Alembic

```
import hou

obj = hou.node("/obj")

ocam = hou.node(hou.ui.selectNode(node_type_filter=hou.nodeTypeFilter.ObjCamera))

reslist = ["1920x1080", "3840x2160", "3072x2109", "2224x1548", "Keep Original", "Custom"]
sl = hou.ui.selectFromList(reslist, message="choose resolution", sort=True, exclusive=True)
stopval = sl[0]
resolution = reslist[stopval]
if resolution is "Keep Original":
    pass
elif resolution is "Custom":
    custom = hou.ui.readInput("Enter resolution as #x# format, ie: 1920x1080. The x is needed.", title="Enter Resolution")
    resolution = custom[1]
    ocam.parm("resx").set(resolution.split("x")[0])
    ocam.parm("resy").set(resolution.split("x")[1])

else:
    ocam.parm("resx").set(resolution.split("x")[0])
    ocam.parm("resy").set(resolution.split("x")[1])

try:
    shotinfo = hou.node("/obj/SHOTINFO")
    backplate = shotinfo.parm("backplate")
except:
    backplate = " "
    pass

camName = ocam.name() + "_baked"
#setback = ocam.parm("vm_background").set(backplate)
tcam = obj.createNode("cam", camName)
tcam.moveToGoodPosition()
```

```
#copy keyframes
cam_xform=["tx", "ty", "tz", "rx", "ry", "rz"]
cam_parms=["resx", "resy", "aspect", "focal", "aperture", "orthowidth", "shutter", "focus", "fstop"]
tcam.parm("vm_background").set(backplate)

parms_bake = list()
parms_bake.extend(cam_xform)
parms_bake.extend(cam_parms)
start = hou.playbar.playbackRange()[0]
end = hou.playbar.playbackRange()[1]

with hou.undos.group("bake cam"):
    for x in range(int(start), int(end + 1)):
        hou.setFrame(x)
        tcam.setWorldTransform(ocam.worldTransform())
        for p in parms_bake:
            parm = tcam.parm(p)
            if parm.name() in cam_xform:
                parm.setKeyframe(hou.Keyframe(parm.eval()))
            else:
                parm.setKeyframe(hou.Keyframe(ocam.parm(p).eval()))
```

# Get frame range from alembic

This script should be added to a button on a node (thats why it's funnyily formated)

```
import _alembic_hom_extensions as ahe; import hou; anode = hou.pwd(); cam = anode.parm("camera").eval();
fpath = hou.node(cam).parm("fileName"); ver = fpath.eval().split("_")[-1].split("/")[0]; print(ver); name =
hou.node(cam).children() ; print(name[0]); anode.parm("cameraVer").set(ver); name = str(name[0]);
anode.parm("cameraName").set(name); alembicpath= fpath.eval(); timerange =
ahe.alembicTimeRange(alembicpath); start_time=timerange[0]*hou.fps(); end_time = timerange[1]*hou.fps();
anode.setParms({"framemin":start_time, "framemax":end_time})
```

# Example On Node Buttons

This is how a button on a non-adminned node needs to be laid out:

import hou (probably not needed) ; do something ;

This grabs frame range from supplied alembic camera, updates names, etc:

```
import _alembic_hom_extensions as ahe; import hou; anode = hou.pwd(); cam = anode.parm("camera").eval();
fpath = hou.node(cam).parm("fileName"); ver = fpath.eval().split("_")[-1].split("/")[0]; print(ver); name =
hou.node(cam).children() ; print(name[0]); anode.parm("cameraVer").set(ver); name = str(name[0]);
anode.parm("cameraName").set(name); alembicpath= fpath.eval(); timerange =
ahe.alembicTimeRange(alembicpath); start_time=timerange[0]*hou.fps(); end_time = timerange[1]*hou.fps();
anode.setParms({"framemin":start_time, "framemax":end_time})
```

This sets frame range from ranges on node:

```
import hou; anode = hou.pwd(); start = anode.parm("framemin").eval(); end = anode.parm("framemax").eval();
hou.playbar.setFrameRange(start, end); hou.playbar.setPlaybackRange(start, end)
```

This grabs info from animation alembic:

```
import hou; anode = hou.pwd(); anim = anode.parm("anim").eval(); fpath = hou.node(anim).parm("fileName");
ver = fpath.eval().split("_")[-1].split("/")[0]; name = hou.node(anim) ; anode.parm("animVer").set(ver); name =
```

```
str(name); anode.parm("animName").set(name);
```

oneliner for-loop -- updates name by index (not complete, need inputs):

```
i = 0; [cn.parm("name" + str(i := i + 1)).set(x.split("/)[-1]) for x in nodes]
```



# Send to Tops

```
import hou
nodes = hou.selectedNodes()
topnet = hou.node("/obj/topnet1")
if not topnet:
    topnet = hou.node("/obj").createNode("topnet")
    topnet.setName("topnet1")
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    fstart = x.parm("f1").eval()
    fend = x.parm("f2").eval()
    if x.type().name() == "rop_geometry":
        ver = x.parm("vp_version")
        path = x.path()
    elif x.type().name() == "rop_alembic":
        ver = x.parm("vp_version")
        path = x.path()
    elif x.type().name() == "filecache::2.0":
        path = x.path() + "/render"
        ver = x.parm("vp_version")
    else:
        ver = x.parm("version")
        path = x.path()

    topcache = topnet.createNode("ropfetch")
    try:
        if x.parm("cachesim").eval() is 1:
            topcache.parm("batchall").set(1)
            topcache.setColor(hou.Color(.5,0,0))
        else:
            topcache.parm("framesperbatch").set(15)
            topcache.setColor(hou.Color(0,.5,0))
    except:
        if x.parm("initsim").eval() is 1:
```

```
    topcache.parm("batchall").set(1)
    topcache.setColor(hou.Color(.5,0,0))
else:
    topcache.parm("framesperbatch").set(15)
    topcache.setColor(hou.Color(0,.5,0))
p = hou.IntParmTemplate("version", "Version", 1, min=1, max=40)
g = topcache.parmTemplateGroup()
g.insertAfter("pdg_servicename", p)
topcache.setParmTemplateGroup(g)
topcache.parm("version").set(ver)
topcache.parm("roppath").set(path)
topcache.setName(name)
```

# Set Frame Range without Script

```
import hou; anode = hou.pwd(); start = anode.parm("framemin").eval(); end = anode.parm("framemax").eval();  
hou.playbar.setFrameRange(start, end); hou.playbar.setPlaybackRange(start, end)
```

# ROP

PostRender open MPLAY:

```
import os; img_path = "`chs("picture")`.replace("$F", "\\*"); os.system("mplay %s" % img_path)
```

# Pull version from hipname

Can be used in a parameter. Returns a integer.

```
import hou, re

version = re.findall('_v\d+', hou.hipFile.basename())[0]

version = int(re.findall('\d+', version)[0])

return version
```

# Get Frame Size of Image File

```
node= hou.pwd(); bg=node.parm("image").eval(); res=houd.imageResolution(bg);  
node.parm("framesizex").set(res[0]); node.parm("framesizey").set(res[1]);
```

# Create Agent from built in mocap rig - Simple

This will take a test mocap rig 3 built in to houdini, create an agent, add agent clips from the built in library (must be in your scene already), and lay everything out.

```
import hou

obj = hou.node("/obj")
agentname = hou.ui.readInput("Agent Name", title="Name")
agentname = agentname[1]

agentpNode = obj.createNode("geo")
agentNode = agentpNode.createNode("agent")

agentpNode.setName(agentname)
agentNode.setName(agentname)
agentnet = agentpNode

inputMoc = hou.ui.selectNode(title="Select Character Rig to base agent on", multiple_select=False,
node_type_filter=houd.nodeTypeFilter.ObjSubnet)

agentNode.parm("agentname").set(agentname)
agentNode.parm("objsubnet").set(inputMoc)

#clips = hou.ui.selectNode(multiple_select=True, node_type_filter=houd.nodeTypeFilter.Obj)
clips = hou.ui.selectNode(title="Select all clips - mocap biped 3 rigs", multiple_select=True,
node_type_filter=houd.nodeTypeFilter.ObjSubnet)
agentclip = agentnet.createNode("agentclip")
clipprops = agentnet.createNode("agentclipproperties")

clipnum = len(clips)
clipcount = 1
```

```
agentclip.parm("locomotionnode").set("Hips")
```

```
#print(clipnum)
```

```
for x in clips:
```

```
    node = hou.node(x)
```

```
    name = node.name()
```

```
    path = str(x)
```

```
    nframes = node.parm("nFrames")
```

```
    fs =hou.playbar.timelineRange()[0]
```

```
    fe = int(fs) + int(nframes.eval())
```

```
    agentclip.parm("framerange" + str(clipcount) + "_1").deleteAllKeyframes()
```

```
    agentclip.parm("framerange" + str(clipcount) + "_2").deleteAllKeyframes()
```

```
    agentclip.parm("clips").set(clipnum)
```

```
    agentclip.parm("name" + str(clipcount)).set(name)
```

```
    agentclip.parm("objsubnet" + str(clipcount)).set(path)
```

```
    agentclip.parm("framerange" + str(clipcount) + "_1").set(fs)
```

```
    agentclip.parm("framerange" + str(clipcount) + "_2").set(fe)
```

```
    agentclip.parm("converttoinplace" + str(clipcount)).set(True)
```

```
    clipprops.parm("numclips").set(clipnum)
```

```
    clipprops.parm("clipname_" + str(clipcount)).set(name)
```

```
    clipprops.parm("enableblending_" + str(clipcount)).set(True)
```

```
    clipprops.parm("framesbefore_" + str(clipcount)).set("5")
```

```
    clipprops.parm("framesafter_" + str(clipcount)).set("5")
```

```
    clipcount = clipcount+1
```

```
agentclip.setFirstInput(agentNode)
```

```
clipprops.setFirstInput(agentclip)
```

```
agentpNode.layoutChildren()
```



# Send selected nodes to new object (fancy way to create object merges)

```
import hou
nodes = hou.selectedNodes()
destnode = hou.node(hou.ui.selectNode(title="select destination node"))
for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    objmergenode = destnode.createNode("object_merge")
    objmergenode.parm("objpath1").set(path)

    objmergenode.setName(name)
    objmergenode.setColor(hou.Color(0,1,0))
```

# Send nodes to new alembic export

```
import hou
nodes = hou.selectedNodes()
destnode = hou.node("/obj/EXPORT")
if not destnode:
    destnode = hou.node("/obj").createNode("geo")
    destnode.setName("EXPORTS")

for x in nodes:
    name = x.name()+"_"+str(x.parent())
    path= x.path()
    objmergenode = destnode.createNode("object_merge")
    objmergenode.parm("objpath1").set(path)

    objmergenode.setName(name)
    objmergenode.setColor(hou.Color(0,1,0))

    alembicrop = destnode.createNode("rop_alembic")
    alembicrop.setName(str(x.parent()))
    alembicrop.parm("trange").set(1)
    alembicrop.parm("f1").deleteAllKeyframes()
    alembicrop.parm("f1").set(int("1001"))
    alembicrop.parm("build_from_path").set(1)
    alembicrop.setInput(0, objmergenode)
    destnode.layoutChildren()
```

# TOPs - symlink output file of parent

```
exportFile = str(work_item.expectedInputFiles[0])  
dir = os.path.dirname(exportFile)  
newFile = os.path.join(dir, "cache.abc")  
  
os.symlink(exportFile, newFile)
```

# Copy Text to Clipboard example

This example I make a dictionary and copy to clipboard. I also gather a frame range from files on disk.

```
#needed: name, path, start, end
import hou, os
from pathlib import Path

def getinfo():
    pathname = hou.ui.selectFile(collapse_sequences=True)
    filename = Path(pathname.split(".")[0])
    parent = filename.parent

    #get frame range
    filenames = [file.name.split(".")[2] for file in parent.iterdir() if file.is_file()]
    start = min(int(i) for i in filenames)
    end = max(int(i) for i in filenames)

    #reformatting stuff
    name = str(filename).split("/")[1]
    path = str(filename)+". "

    return name, path, start, end

def wrangle():
    wranglenode = hou.selectedNodes[0]
    #assign variables to function so we can use them globally
    name, path, start, end = getinfo()

    #format stuff
    q = ""
    textForWrangle = f'dict {name}; \n {name}[\n{name}\'] = {q}{name}{q}; \n {name}[\npath\'] = {q}{path}{q};
```

```
\n {name}[\\"startFrame\\"] = {start}; \n {name}[\\"endFrame\\"] = {end}; \n append(chars,{name}); '
```

```
print(textForWrangle)
```

```
#copy to clipboard
```

```
hou.ui.copyTextToClipboard(textForWrangle)
```

```
hou.ui.displayMessage(title="Copied", text=f"Here is what was copied to clipboard: {textForWrangle} \n")
```